### Interferometric observations of microlensing events

**Clément** Ranc

Institut d'Astrophysique de Paris & RoboNet collaboration

Arnaud Cassan, Vincent Coudé du Foresto, Stephen Ridgway, Olivier Absil, Olivier Wertz, Jean-Baptiste Le Bouquin, Nic Scott, Rachel Street, Jean Surdej,

CHARA Meeting 2016, Nice – Tuesday March, 15th

## Gravitational microlensing

• Deflection of light due to the gravity of a star. microlens





### • Single lens: 2 images

Point source: 2 isolated images. Finite source: 2 isolated images per edge point.

Angular scale: Einstein radius  $\theta_E$ 

Magnification as a function of time





 $\Xi = \frac{\mathsf{G}\mathsf{M}}{c^2\mathsf{R}} \sim 10^{-5}$ 

Low probability of alignement

• Compactness red dwarf:

• Creation of multiple

 $D_{\rm S} \approx 8 \, \rm kpc$ 

 $\theta_{\rm E} \approx 1 \, {\rm mas}$ 

 $D_{\rm L} \in [0.5; 8] \, \rm kpc$ 

images



### Planetary microlensing



#### • Binary lens equation: 3 or 5 images



Queloz (2006)

• Images not resolved by one telescope

• Central role of the caustics



### Microlensing network of telescopes in 2015

• A need for a continuous follow-up to catch the planetary features.



- Light curve: flux from the source as a function of time
- New networks and new network of robotic telescopes

Microlensing among exoplanets detection techniques





### Parameters determination in microlensing



Resolving the multiple images using an interferometer



 $\theta_{\rm E} \leq 1 \, {\rm mas}$  $t_{\rm E} \approx 50 \,\mathrm{days}$  $D_{\rm L} \approx 0.5 - 8 \, \rm kpc$  $D_{\rm S} \approx 8 \, \rm kpc$ 

Images cannot be resolved individually...

... but the separation between the images is at reach of 100m baseline interferometers

 $t-t_0$  (jours)

## Probing the (u,v)-plane using interferometry



### ♦ An interferometer: N telescopes —> N(N-1)/2 baselines





Credit: CHARA website

#### ✦ Goal: measuring visibility of an extended source

Visibility related to the "source" intensity profile (van Cittern-Zernike theorem)

$$\mathcal{V}\left(\frac{B_x}{\lambda_0}, \frac{B_y}{\lambda_0}\right) = \frac{\iint I(\theta_x, \theta_y) e^{-i2\pi \frac{B \cdot \theta}{\lambda_0}} d\theta_x d\theta_y}{\iint I(\theta_x, \theta_y) d\theta_x d\theta_y} = \frac{\mathrm{FT}\left[I\right](u, v)}{\mathrm{FT}\left[I\right](0, 0)} \qquad (u, v): \text{ spatial frequencies}$$

$$FT[I](u,v) = \iint I(x,y) e^{-i2\pi(ux+vy)} dxdy$$

### Single lens model



### ✦ Previous study: Delplancke et al. (2001)

Two point-source images: 
$$f(x) = R \ \delta(x_0 - S/2) + \delta(x_0 + S/2)$$
  
Visibility:  $V(u) = \frac{\sqrt{R^2 + 1 + 2 R \cos(2\pi uS)}}{R+1}$   $R = \frac{A+1}{A-1}$   $u = B/\lambda$ 



✦ For N point-images:

### **Closure** phase



### ✦ Previous study: Dalal & Lane (2003)

One baseline : problem to determine phase of the visibility

 $ar{V} = |\hat{V}| e^{i(\phi_{12}+\phi_1-\phi_2)}$ 

 $\Phi_{12}:$  intrinsic phase difference between T1 and T2  $\Phi_1$  and  $\Phi_2:$  random phases

**Closure phase with three baselines:** 

 $ar{V}_{123} = |\hat{V}_1||\hat{V}_2||\hat{V}_3|e^{i[\phi_{12}+\phi_{23}+\phi_{31}+(\phi_1-\phi_2)+(\phi_2-\phi_3)+(\phi_3-\phi_1)]} \ = |\hat{V}_1||\hat{V}_2||\hat{V}_3|e^{i(\phi_{12}+\phi_{23}+\phi_{31})} \ .$ 

$$\phi_{123} = \left\{ \frac{(R^2 - R) \sum_{i=1,2,3} \sin[(2\pi/\lambda)\Delta s \cdot B_i]}{1 + R^3 + (R + R^2) \sum_{i=1,2,3} \cos[(2\pi/\lambda)\Delta s \cdot B_i]} \right\}.$$



S/N ratio obtained from astrometry, visibility and closure phase.

### Finite source effects in a single lens



✦ Previous study: Rattenbury and Mao (2005)



$$z_{+,-}(r,\varphi) = \frac{z_{s,0} + r \mathrm{e}^{\mathrm{i}\varphi}}{2} \left[ 1 \pm \sqrt{1 + \frac{4}{g(\varphi)}} \right]$$

$$\mu_{\text{tot}} = \frac{1}{\pi \rho_{\star}^2} \int_0^{2\pi} \left[ -Y_+(\varphi) \frac{\mathrm{d}X_+(\varphi)}{\mathrm{d}\varphi} + Y_-(\varphi) \frac{\mathrm{d}X_-(\varphi)}{\mathrm{d}\varphi} \right] \mathrm{d}\varphi$$

Point source (dashed) versus finite source (limb-darkening and uniform)



## Visibility: when interferometry joins microlensing



Visibility related to the "source" intensity profile (van Cittern-Zernike theorem)

$$\mathcal{V}\left(\frac{B_x}{\lambda_0}, \frac{B_y}{\lambda_0}\right) = \frac{\iint I(\theta_x, \theta_y) e^{-i2\pi \frac{B \cdot \theta}{\lambda_0}} d\theta_x d\theta_y}{\iint I(\theta_x, \theta_y) d\theta_x d\theta_y} = \frac{\mathrm{FT}\left[I\right](u, v)}{\mathrm{FT}\left[I\right](0, 0)}$$
$$\mathrm{FT}\left[I\right](u, v) = \iint I(x, y) e^{-i2\pi(ux + vy)} dx dy$$

(u,v): spatial frequencies

- $\theta_{\rm E}$  is now a vectorial quantity (Gould & Yee, 2014)
- Interferometry point of view: **visibility** is related to the **Einstein angular radius**

$$ux + vy \equiv \frac{B}{\lambda_0} \cdot \boldsymbol{\theta} \equiv -\boldsymbol{k} \cdot \boldsymbol{\theta}$$

'Einstein (u,v) plane": link between microlensing and interferometry.  $\begin{pmatrix} u \\ v \end{pmatrix} \equiv \begin{pmatrix} \boldsymbol{\theta}_{\mathrm{E}} \cdot \boldsymbol{k} \\ \boldsymbol{\theta}_{\mathrm{E}} \times \boldsymbol{k} \end{pmatrix} = \begin{pmatrix} \theta_{\mathrm{E},N}k_{N} + \theta_{\mathrm{E},E}k_{E} \\ \theta_{\mathrm{E},N}k_{E} - \theta_{\mathrm{E},E}k_{N} \end{pmatrix} = \begin{pmatrix} \theta_{\mathrm{E},\parallel}k_{\parallel} + \theta_{\mathrm{E},\perp}k_{\perp} \\ \theta_{\mathrm{E},\parallel}k_{\perp} - \theta_{\mathrm{E},\perp}k_{\parallel} \end{pmatrix}$ 

 $\mathcal{V}_{\mathrm{E}}(u,v) = \frac{\mathrm{F}^{\mathrm{T}}\left[I\right]\left(u,v\right)}{\mathrm{FT}\left[I\right]\left(0,0\right)} \quad \text{with spatial frequencies in units of} \quad \theta_{\mathrm{E}}^{-1}$ 

(Cassan & Ranc 2016, in press, MNRAS)



### Examples of visibility patterns



### ♦ Single lens: 2 images in motion



#### **+** Single lens with strong finite source effects:



$$\operatorname{FT}\left[I\right]\left(u,v\right) = -\frac{i}{2\pi} \oint_{\partial \mathcal{I}} \frac{e^{-i2\pi(uX+vY)}}{v} dX$$



### ♦ B and V are a function of time





"Microlensing" supersynthesis: motion of the images

✦ Spectral coverage



## Simulated constrains on the Einstein radius



#### • Both prediction AND parameters determining after observations.



• Simulating V<sup>2</sup> simultaneously from 6 baselines.



### Simulated constrains on the Einstein radius



• Key step: combining photometric measurements with interferometry



• Interpretation of interferometric observations rely on the photometric light curve.



### ♦ Statistics based on 2011-2014 seasons: 7342 observed events

Estimation of K-mag at the peak after identifying SL and binary lenses.



(Cassan & Ranc 2016, in press, MNRAS)

How many events in 4 years? 26 events with K<10

#### Conversion I-magnitude to K-magnitude

- Microlensing light curve fits
- Absorption in K/I bands (Marshall et al. 2006/Nataf et al. 2013)
- K/I-mag conversion with stellar isochrones (Girardi et al. 2002)
- From microlensing model, K-mag at peak of the event

## A first attempt with CHARA in 2015

- ✦ First test of the full observational strategy.
- The best target of the season (early).
- ✦ VisObs has identified it.
- First alert officially sent by Arnaud Cassan to Stephen Ridgway on May 21st (K<9) on MOA-2015-BLG-020/ OGLE-2015-BLG-0102.
- 6.5 hours later, CHARA was preparing a try.





- Back and forth during 3 days with updates. (K=10.5 on May 24th)
- No observations because of rain.
- ✦ Unique opportunity to test interactions
  - These events do exist!

### **ESO VLTI Proposal**

### ◆ ESO VLTI Proposal, accepted in 2015

- PI: A. Cassan Co-PI: O. Absil, C. Ranc, R. Street, J. Surdej, O. Wertz, J.-B. Le Bouquin
- Pilot project to demonstrate the feasibility of interferometric observations of microlensing events
- VLTI location much better to observe the Galactic Bulge
- ✦ Target of Opportunity observing mode
- ♦ Observing period: April to October
- ♦ VLTI/PIONIER: the only instrument in the Southern hemisphere that combines a mas resolution with a high enough sensitivity



Credit: Max-Planck-Institut für radioastronomie website







http://www.iap.fr/miiriads/VisObs/events.html



#### ✦ Code to colect, order and identify data





#### http://www.iap.fr/miiriads/VisObs/events.html



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### Conclusion

#### ✦ Interferometry to solve degeneracies in microlensing

- Microlensing images can be in principle resolved by 100m-baseline.
- Visibility and closure phase allow an independent constrain on the Einstein angular radius.

#### Observational challenges

- Limiting magnitudes.
- Short notice alert based on real-time modelling.
- Prediction of the peak magnitude in H and K.

### Now, let's try to observe

- Several events can be observed, in principle, every year by the VLTI.
- A first good candidate identified in May 2015: test of the observing strategy.
- ESO/PIONIER/VLTI Proposal accepted.
- Good perspectives for the instrument ESO/Gravity.

# Thank you!