



Software activities shaping the CHARA Array

Narsireddy Anugu + CHARA collaboration

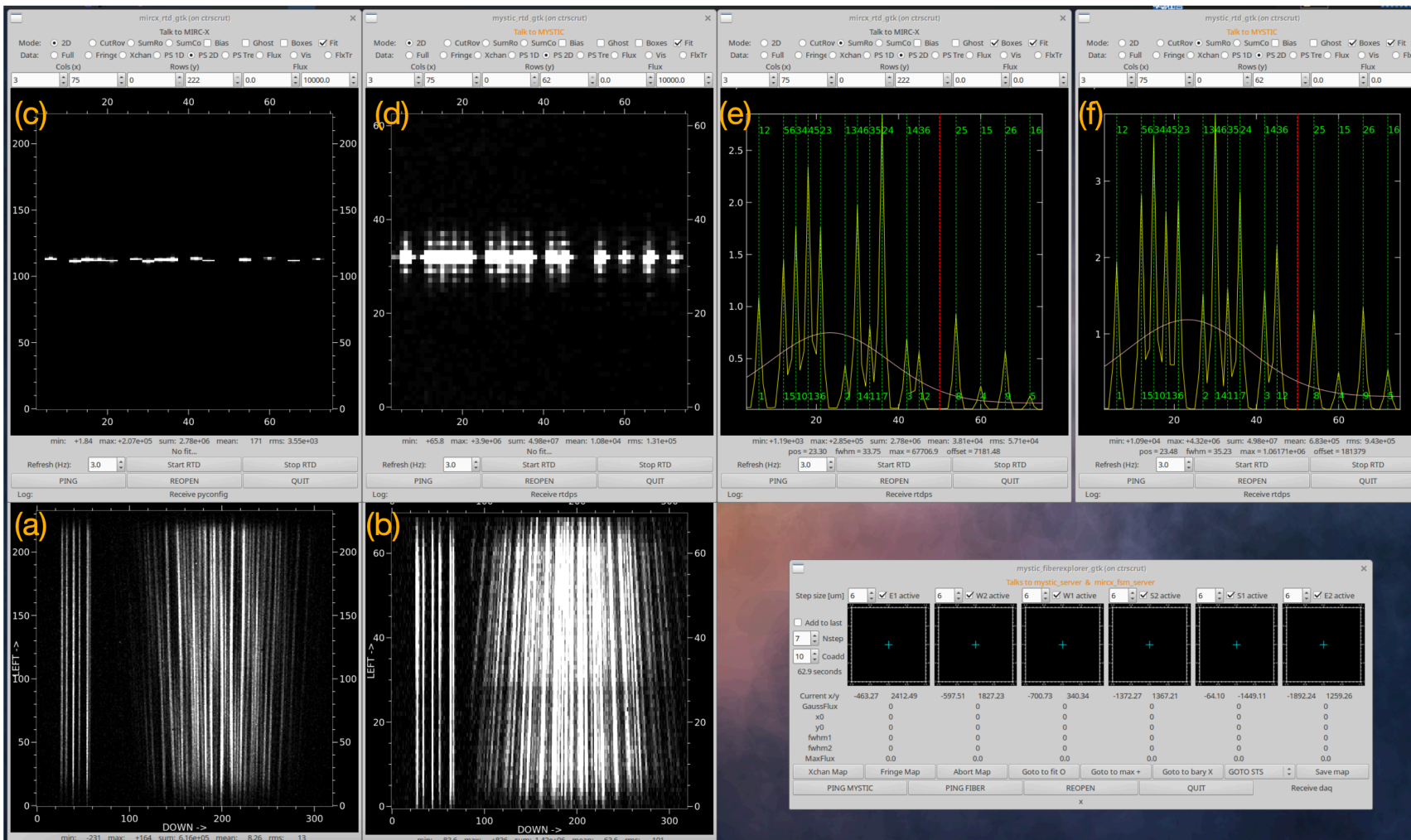
2022 Mar 13



CHARA beam combiners

	Wavelength	# of beams combined	Status
PAVO	R-band	2	In operation
CLASSIC/CLIMB	J+H+K	≤ 3	In operation
MIRC-X/MYSTIC	J+H+K	6	In operation
SPICA	R-band	6	Commissioning phase
SILMARIL	H+K	3	Commissioning phase

1. MIRC-X + MYSTIC

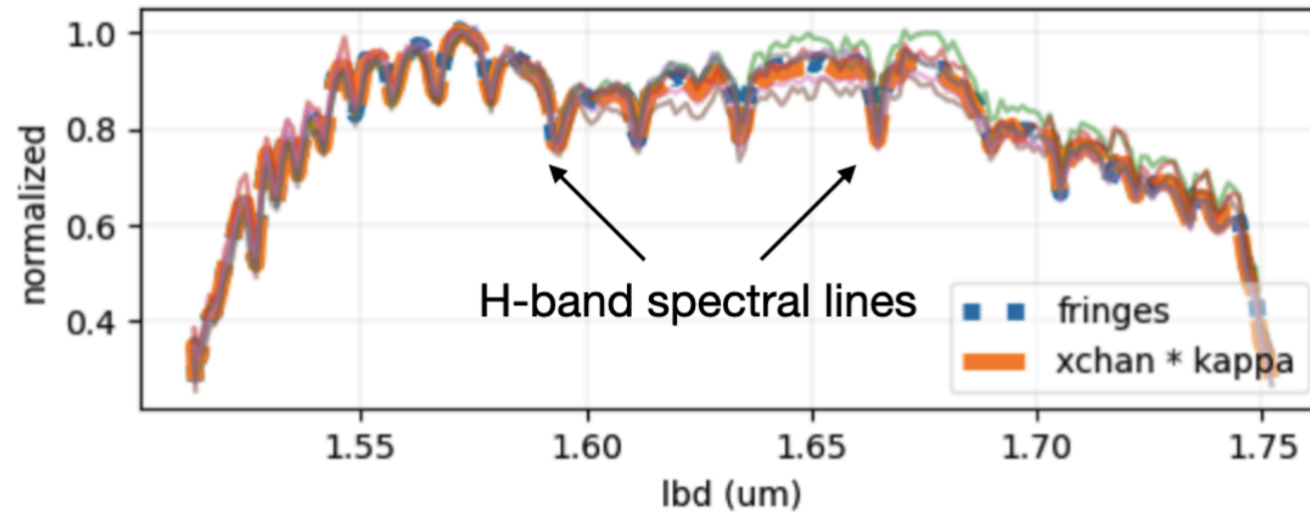
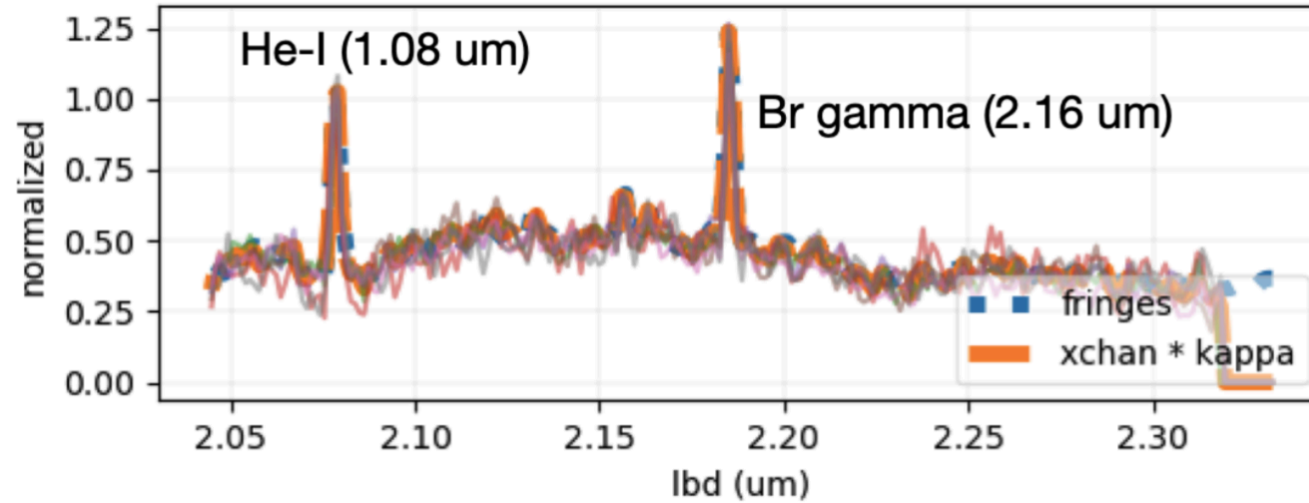


Spectral resolutions:

MIRC-X (R)	MYSTIC (R)
20	20
50	49
102	100
198	278
1170	981
	1724

(See John's talk)

1. MIRC-X + MYSTIC





1. MIRC-X + MYSTIC: Two modes of fringe tracking

(1) Fringe tracker and science beam combiner

Low R — fringe track

High R — science

For example,

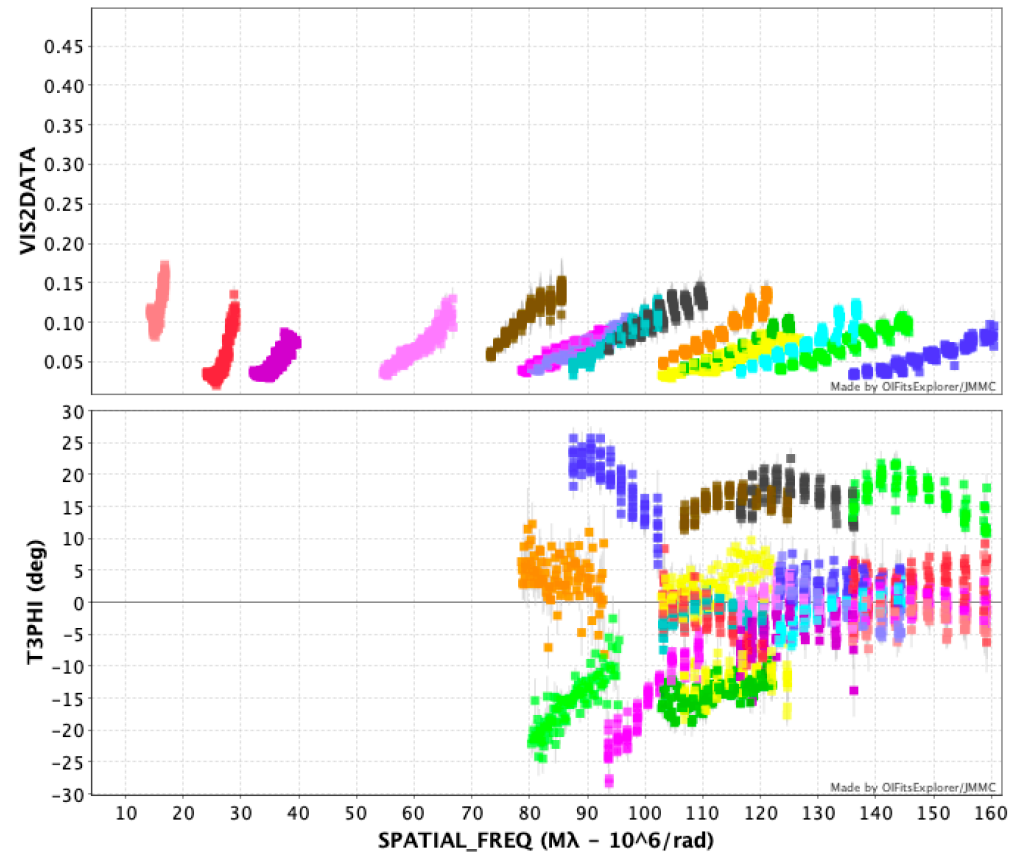
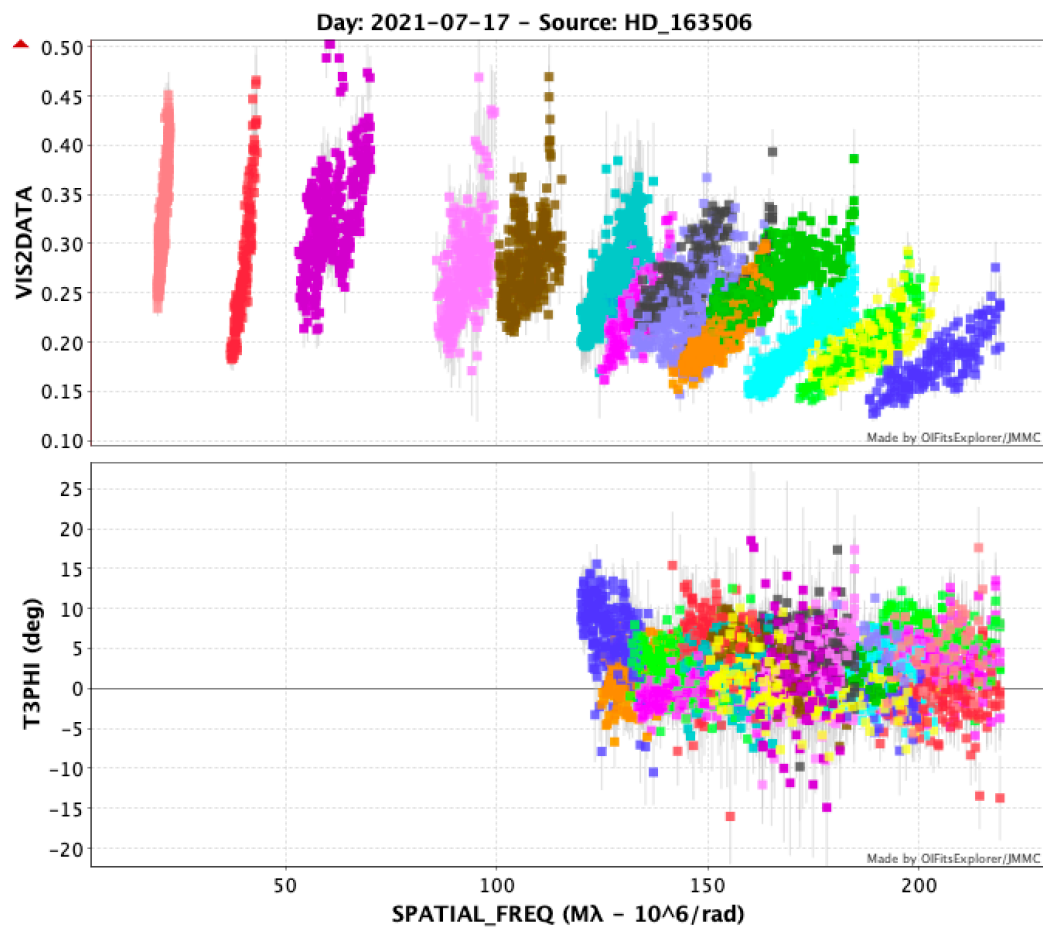
MIRC-X (low-R) and MYSTIC (high-R)

MIRC-X (high-R) and MYSTIC (low-R)

(2) Combined mode: all the information is used for fringe tracking



1. Combined mode for extended objects



2. SILMARIL

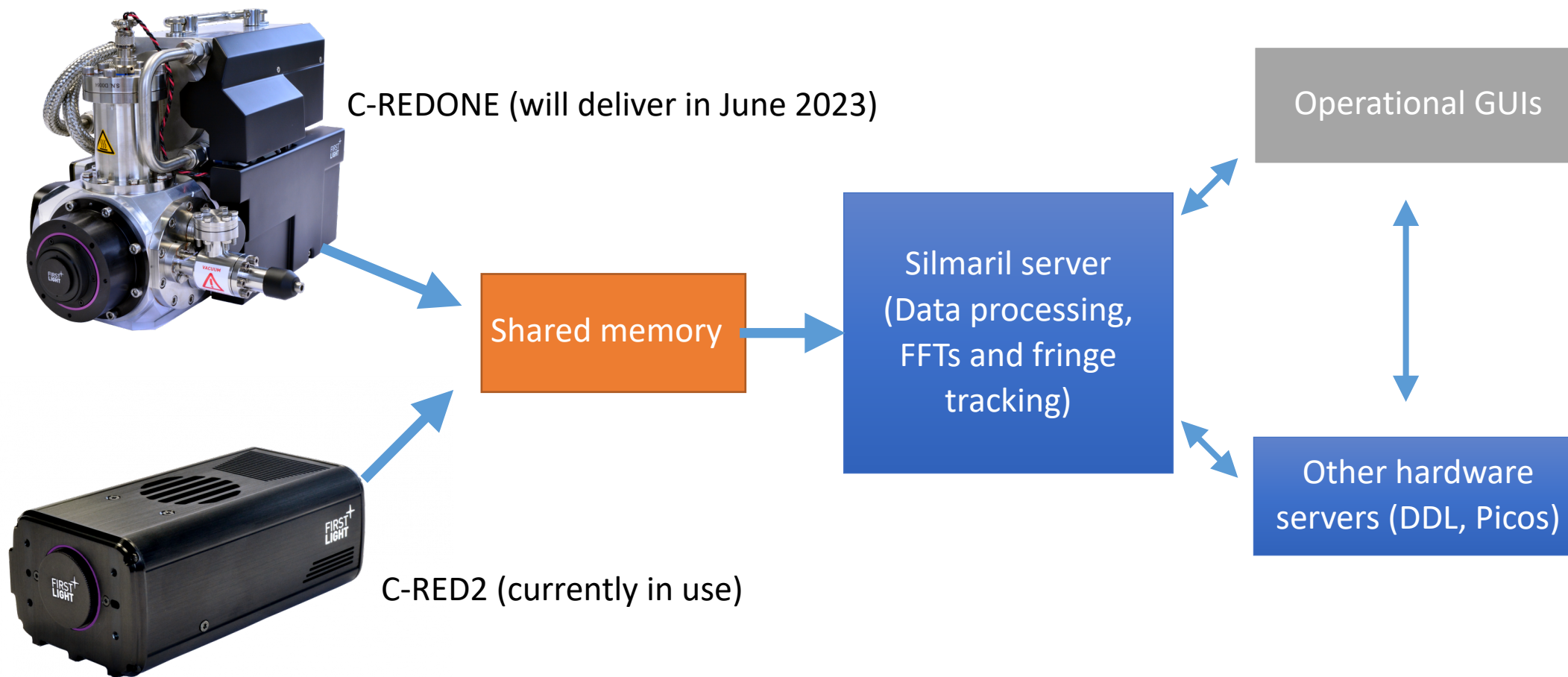
- 3-beam combiner
- CRED ONE camera
- Aimed for sensitivity to observe faint stars
- PI: Theo ten Brummelaar

- We chose minimum development approach by using tested and working code
- We use MIRC-X software and GUIs, since the same camera and also users most familiar with mircx user interface

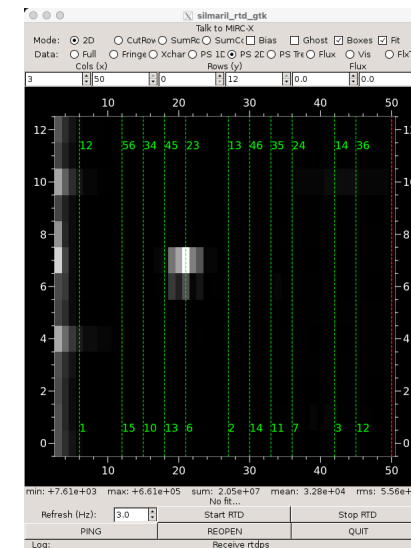
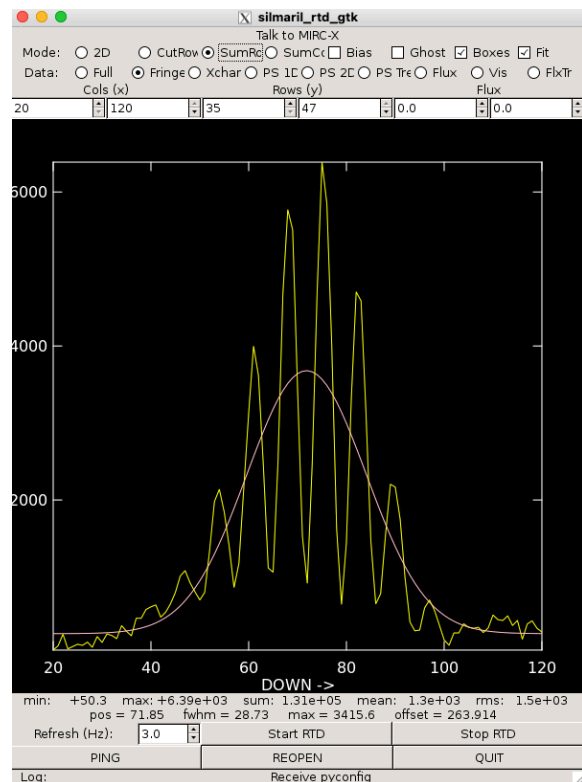
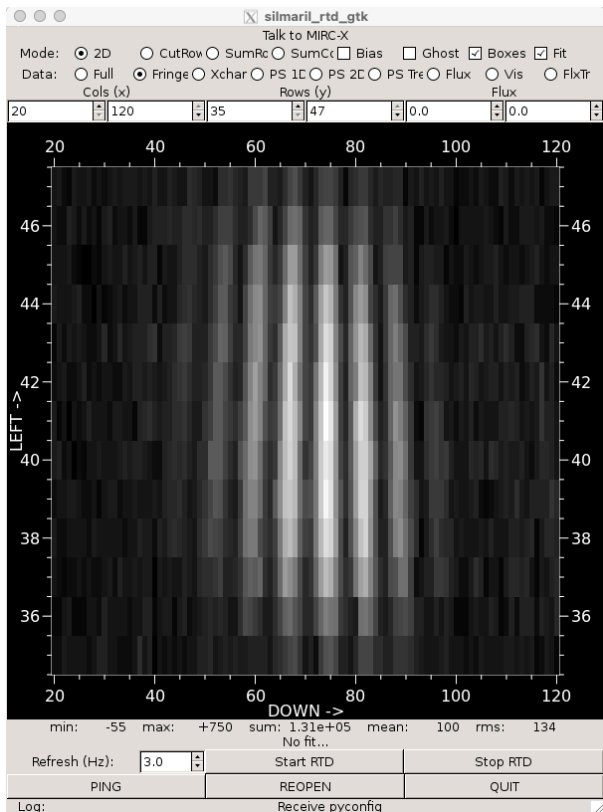
(See Cyprien talk)



2. SILMARIL current status



2. SILMARIL software working with lab STS (see Cyprien talk more details)



silmaril_gdt_gtk

beam	pop	ldc	cart pos error		DL offset	step size	link beams	S1	S2	E1	E2	W1	W2								
S1	5	0	x	MAN	FT	x <<< <	0	0.000	>	>>	0.002	Loop-	Loop+	<input checked="" type="checkbox"/>	S1	-	x	x	x	x	x
S2	4	0	x	MAN	FT	x <<< <	0	0.000	>	>>	0.002	Loop-	Loop+	<input checked="" type="checkbox"/>	S2	2.3	-	x	x	x	x
E1	1	0	x	MAN	FT	x <<< <	0	0.000	>	>>	0.006	Loop-	Loop+	<input checked="" type="checkbox"/>	E1	0.7	0.4	-	x	x	x
E2	6	0	x	MAN	FT	x <<< <	0	0.000	>	>>	0.006	Loop-	Loop+	<input checked="" type="checkbox"/>	E2	0.3	0.2	7.1	-	x	x
W1	3	0	x	MAN	FT	x <<< <	0	0.000	>	>>	0.010	Loop-	Loop+	<input checked="" type="checkbox"/>	W1	0.2	0.5	0.1	0.3	-	x
W2	2	0	x	MAN	FT	x <<< <	0	0.000	>	>>	0.010	Loop-	Loop+	<input checked="" type="checkbox"/>	W2	0.7	0.5	0.2	1.3	25.6	-

gdt Gain: 0.60 0.60 SearchThr: 10.0 FRINGE LOCK CLEAR MATRIX

DLsleep(mas)	S1	S2	S1 E1	S1 E2	S1 W1	S1 W2	S2 E1	S2 E2	S2 W1	S2 W2	E1 E2	E1 W1	E1 W2	E2 W1	E2 W2	W1 W2
OPD:	1.6	12.0	16.0	-28.4	8.6	-23.2	37.9	15.2	-30.8	9.2	39.8	38.4	-22.0	18.4	0.1	
POL_PHI:	x	x	x	x	x	x	x	x	x	x	x	x	x	x	x	x
MEAN VIS:	0.18	0.28	0.16	0.20	0.96	0.22	0.18	0.15	0.21	0.51	0.17	0.00	0.23	0.23	0.37	
DISPERSION:	-15.70	-114.53	-1153.43	-1416.04	1728.80	-2056.72	-823.97	-790.34	-1890.79	-12.40	-565.28	457.14	-1939.46	-1724.39	-12.36	
SIGNAL	46.8	14.1	6.9	4.7	14.9	7.1	4.1	10.0	10.9	142.5	1.0	3.9	5.1	25.2	512.5	
NOISE	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	

GET SEND 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0

Target: UNKNOWN Mag: 0.000000 RA: 00 00 00.00 DEC: 00 00 00.00 HA: x UTC: x

3. Wavelength dispersion control

- With Denis, we developed a dedicated LDC (longitudinal dispersion correction) control
- This server can correct wavelength dispersion for SPICA and also J-band (MIRC-X) observations.
- Code adapted from ople to allow easy to play and for monitoring the computations.

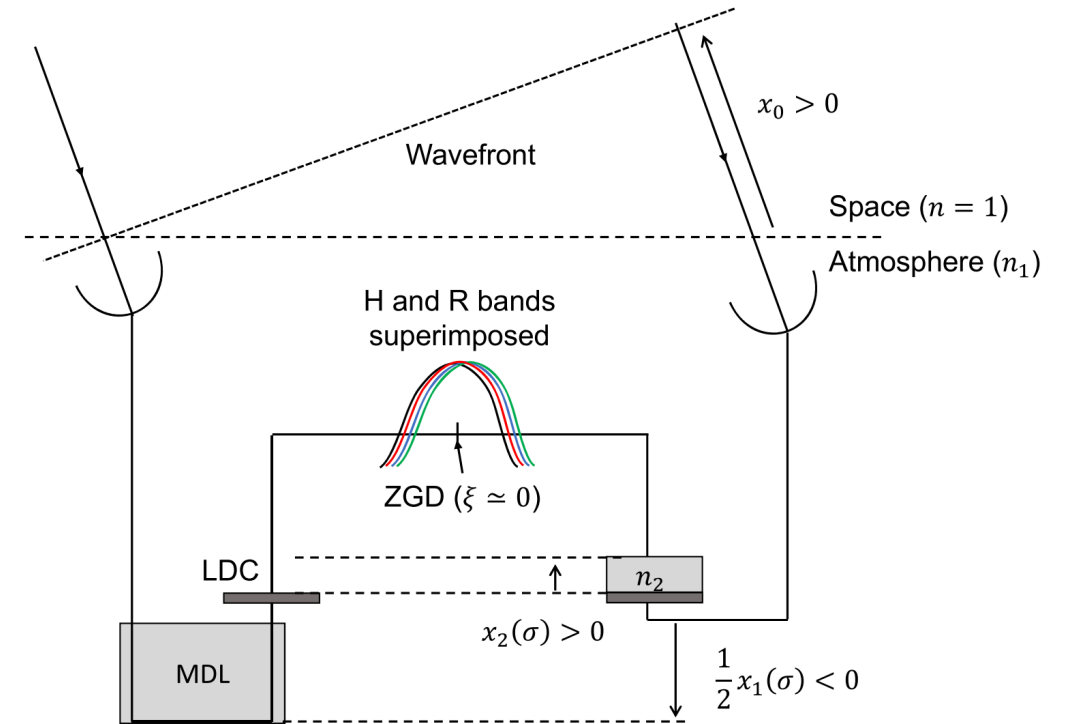
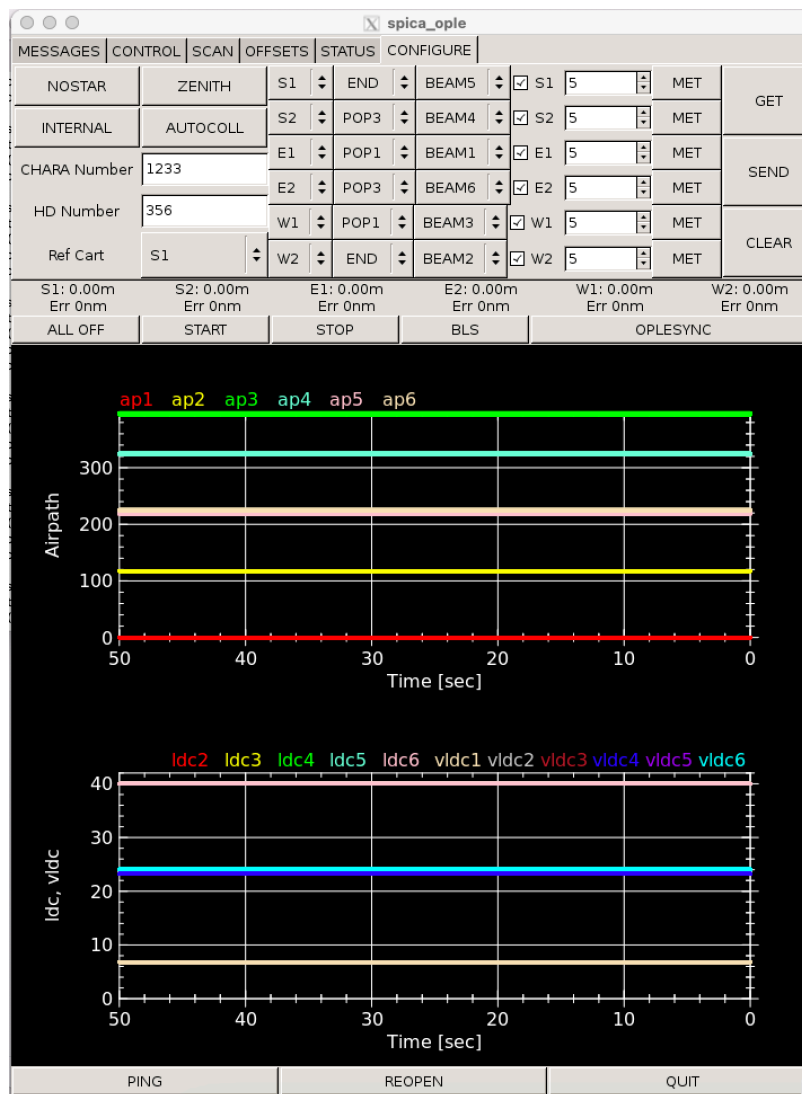


Image credit: Pannetier

(See Denis talk for how its being used)

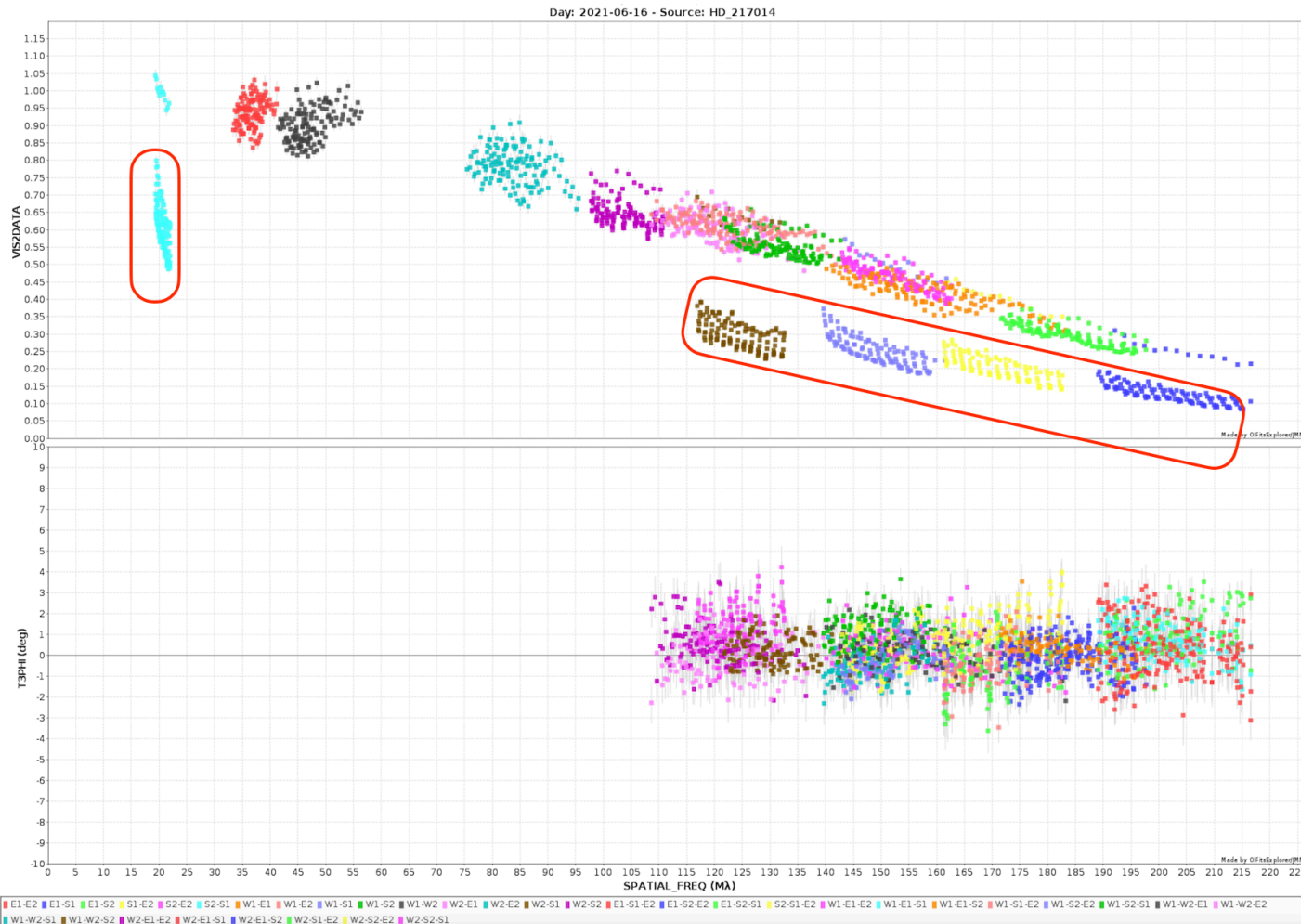


3. Wavelength dispersion control





4. Visibility loss issues

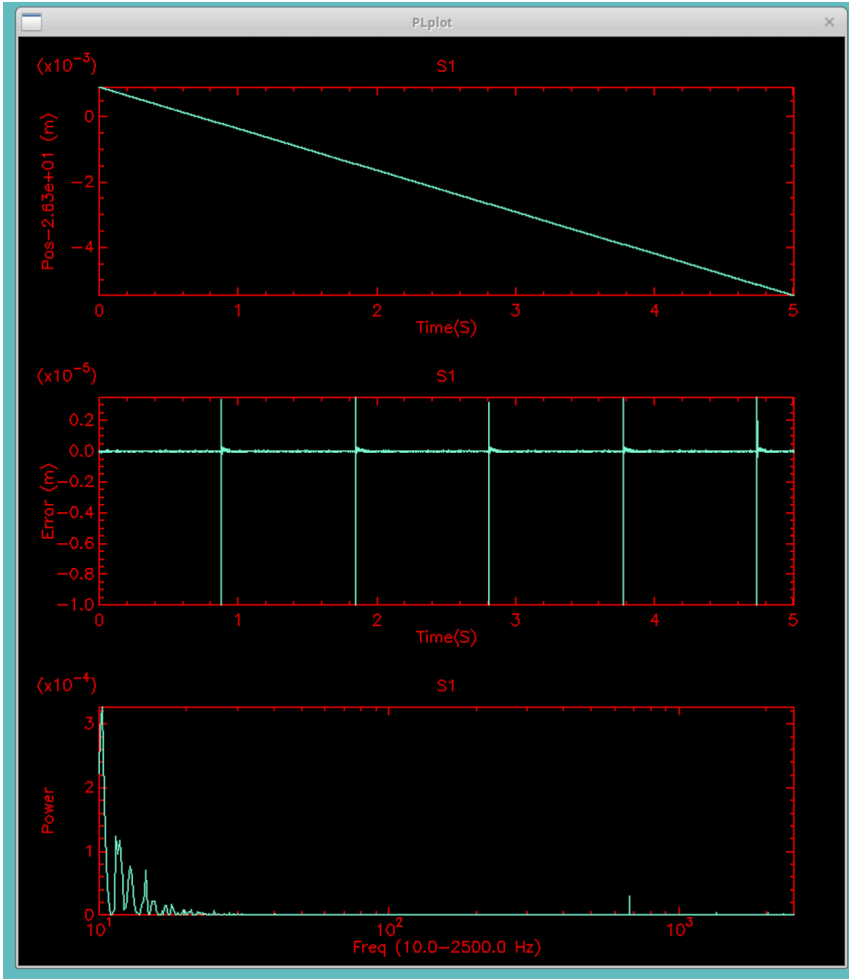


S1 visibility drops

- Between elevation = 45 - 60 and Azimuth ~ 100
- We checked telescope area, tip-tilt and AO systems and they seem NOT introduce any vibrations.
- We narrowed it down to the S1 cart.
- Current solution is keeping S1 as REF

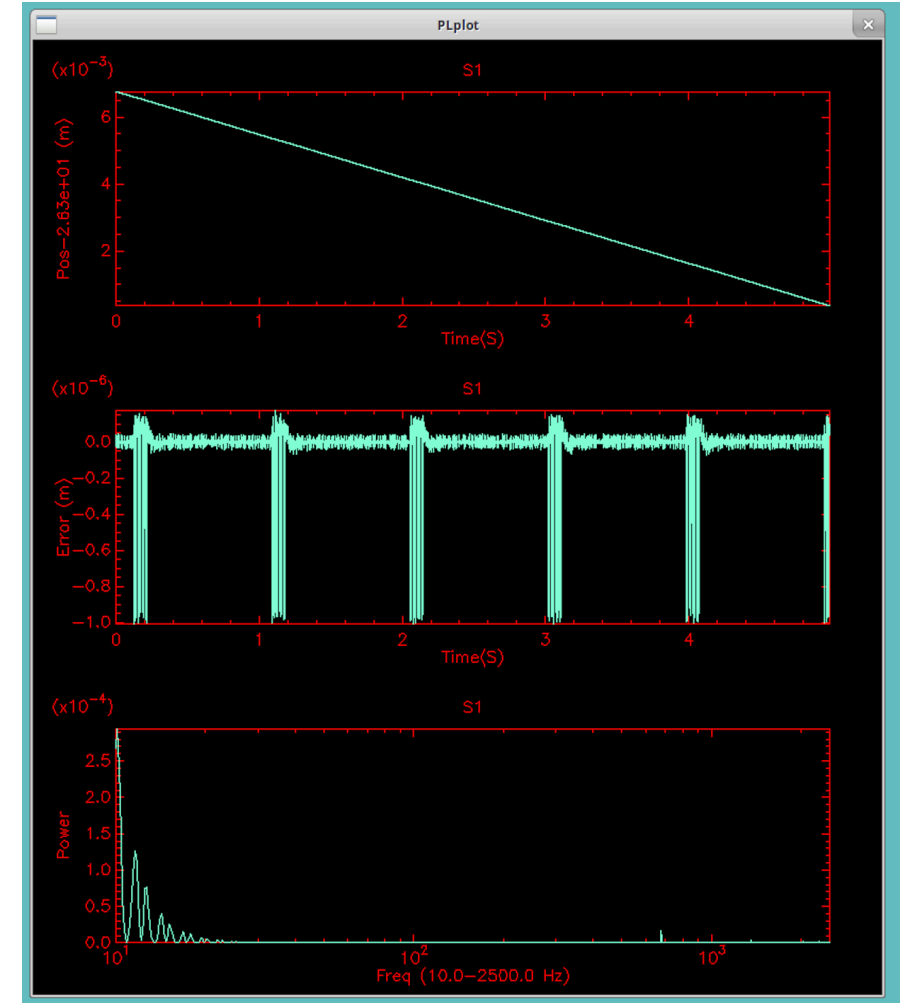


5. Fringe tracking improvements



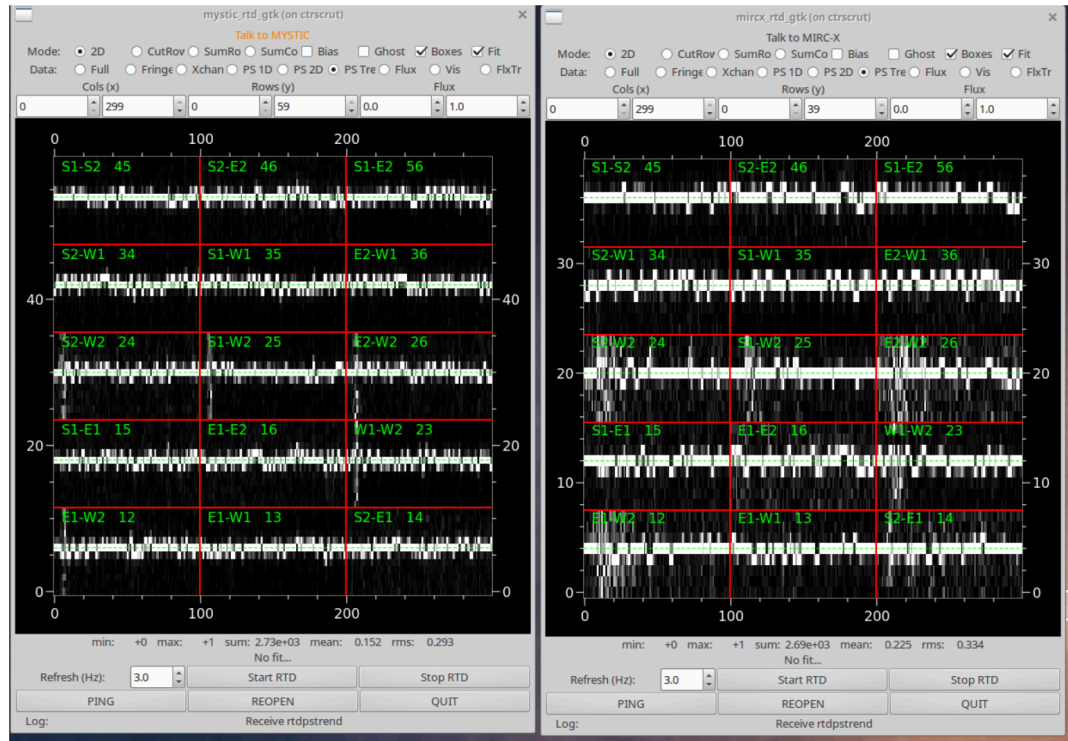
Overshoot > 2um

Ramp offsets ->



Overshoot < 0.1um

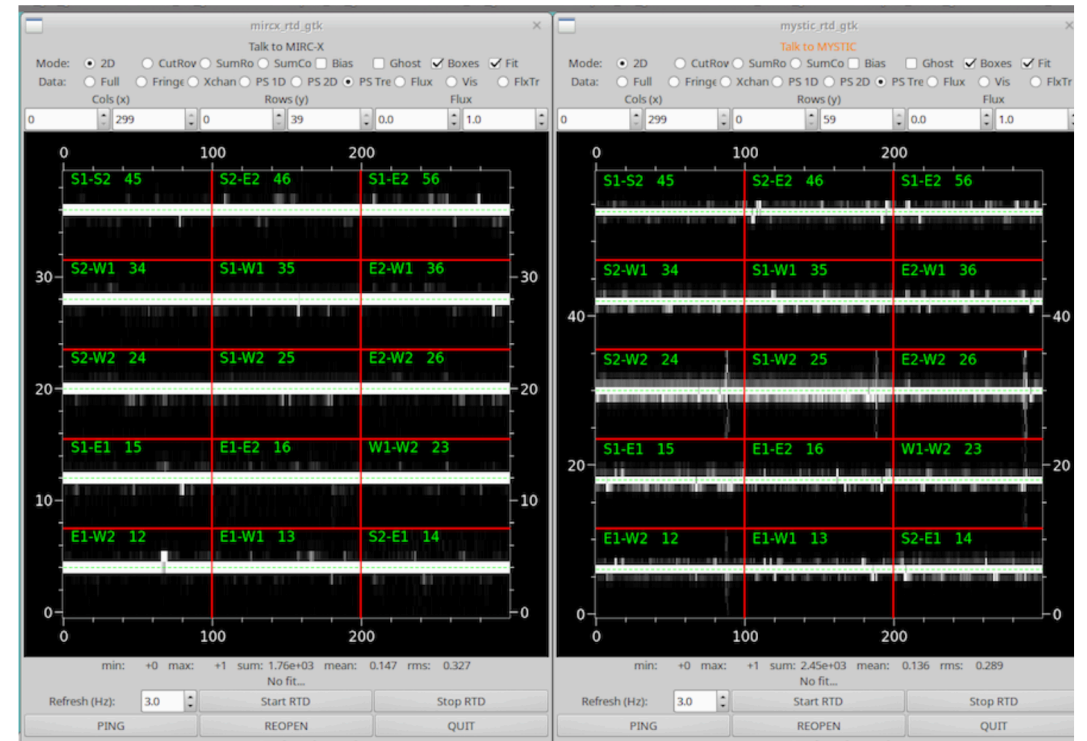
5. Standard (MANUAL) vs new (METBOX-RAMP-FT) fringe tracking



MYSTIC

MANUAL target

MIRC-X

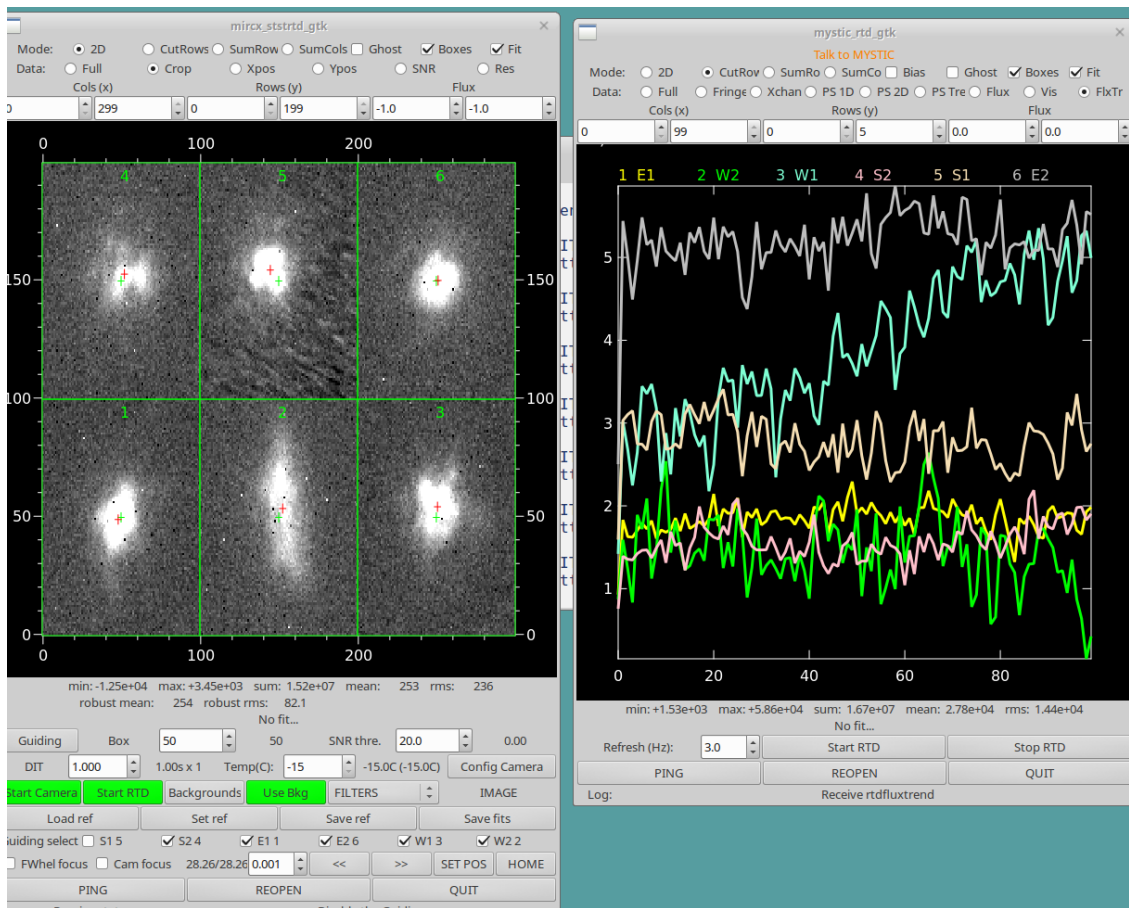


MIRC-X

FT target

MYSTIC

6. Flux stabilization with Star Tracker



Demonstration of beam stabilization
(W1 loop was not closed)

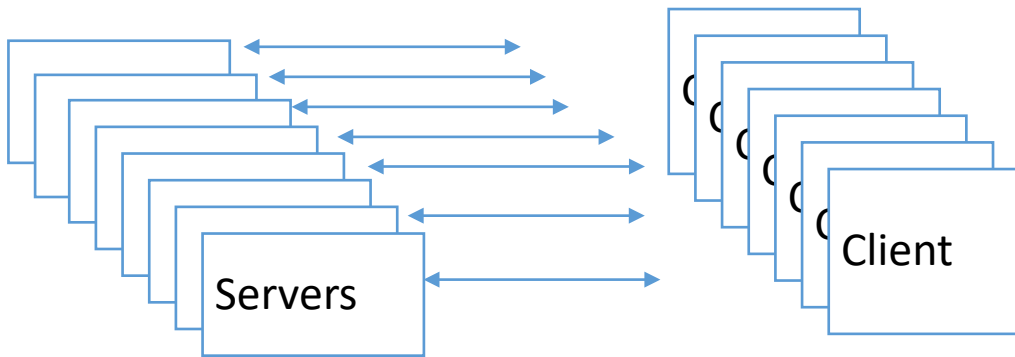
- Along the beam train (>100m), all optics/actuators are in motion due to misalignments and temperature differences
- Which causes the beam drifts
- We track the beams using the Star Tracker and feedback to M7 actuator via labao sensor for stabilization

(See John's talk for more details)

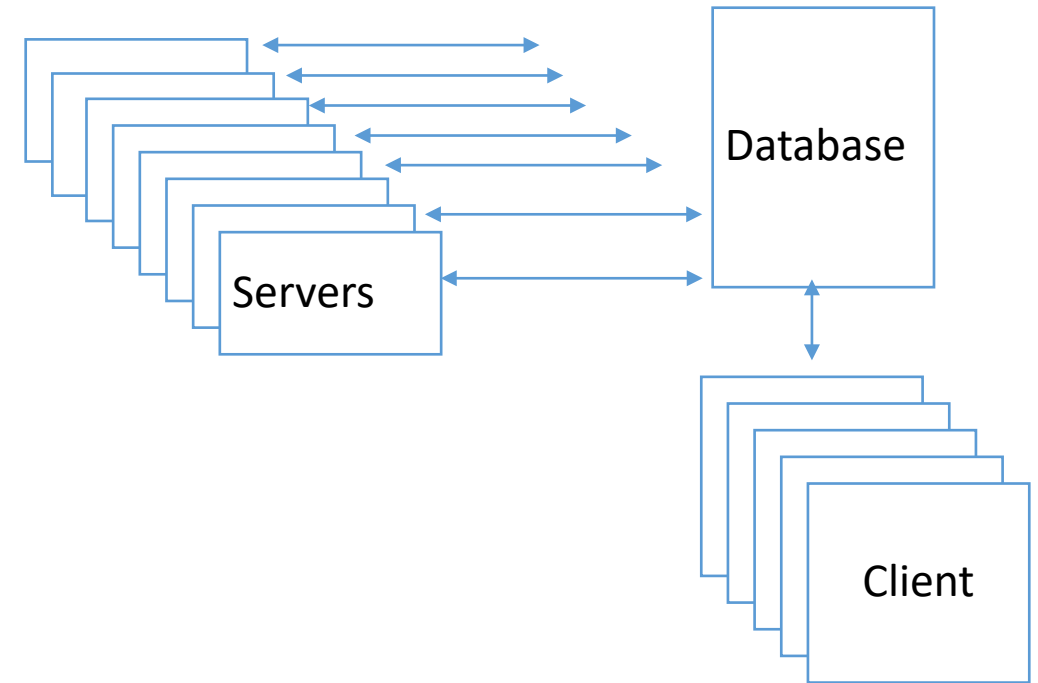


7. CHARA database

Current



With database





Future works



8. CHARA client-server library upgrade

- The CHARA client-server library works great in good network conditions but have problems in slow network
- To solve we attempted **zeromq**, open-source messaging library
- Zeromq is a high-speed, Multi-transport (TCP, UDP, IPC, and web socket ..)
- Zeromq being used for TMT common software
- The zeromq library is built into CHARA software and tested in the lab but need to be tested on-sky
- Rolling over between CHARA classic vs zeromq based client-server, unfortunately complex and abrupt because, we need to install and start 100 applications (including servers and GUIs)



9. CHARA software upgrade To ubuntu 22

Currently we are using Ubuntu 16 LTS (support ended Apr 2021)

- A straightway upgrade of computers will not work as we need to upgrade software of cameralink and DM computer software
- Recent version of Matrox and Bitflow frame grabber software support the Ubuntu 22 LTS. We need to buy license to upgrade them.
- The rest of them are easier but we need to install in one compute and test.