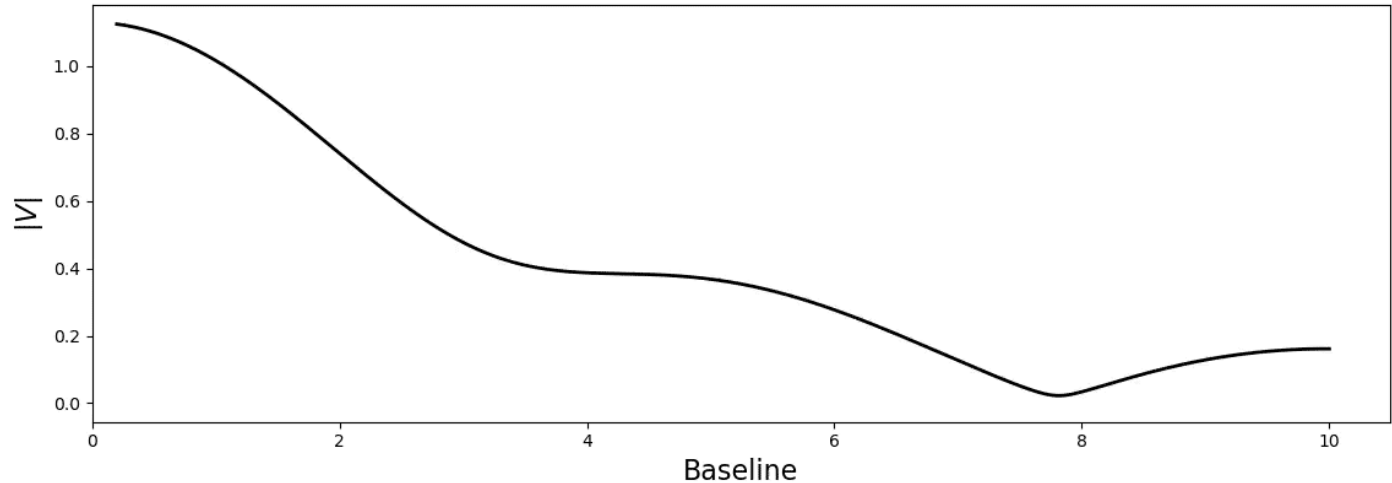
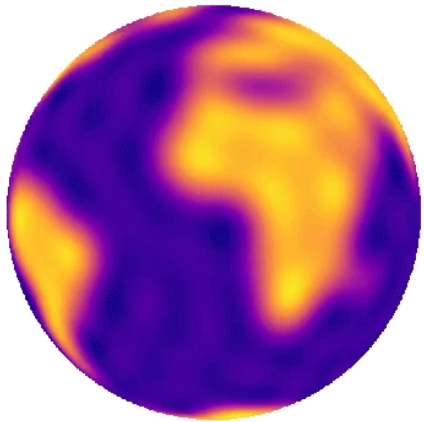


# Harmonix: Analytic models of rotating stars



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# Problem statement

- Understanding stellar surfaces can help solve many enigmas in stellar physics (magnetism, interiors, chemistry)
- Stellar surfaces represent a noise floor for other fields of astrophysics (exoplanet detection, mass measurements & atmospheres)
- Mapping stars interferometrically is *hard*
  - Need very long baselines to image spots
  - Computationally complex to interpret data
  - Difficult to scale to most stars (e.g. main-sequence stars)
  - Need to widen in scope to tackle the above science problems

# Approaches to interferometric stellar mapping

Forwards model:

1. See if there exists an analytic model for the star you're working with (limb darkened disk)
2. If not, discretize star into a tessellation on a sphere
3. Rotate, project & take numerical Fourier transform

Many tried-and-tested models! (SIMTOI<sup>1</sup>, rotir.jl<sup>2</sup>, SURFING<sup>3</sup>)

Fit these non-analytic forwards models to data (the inverse problem)

Requires optimizing over >1000 parameters

Intractable to find uncertainties and degeneracies in the maps

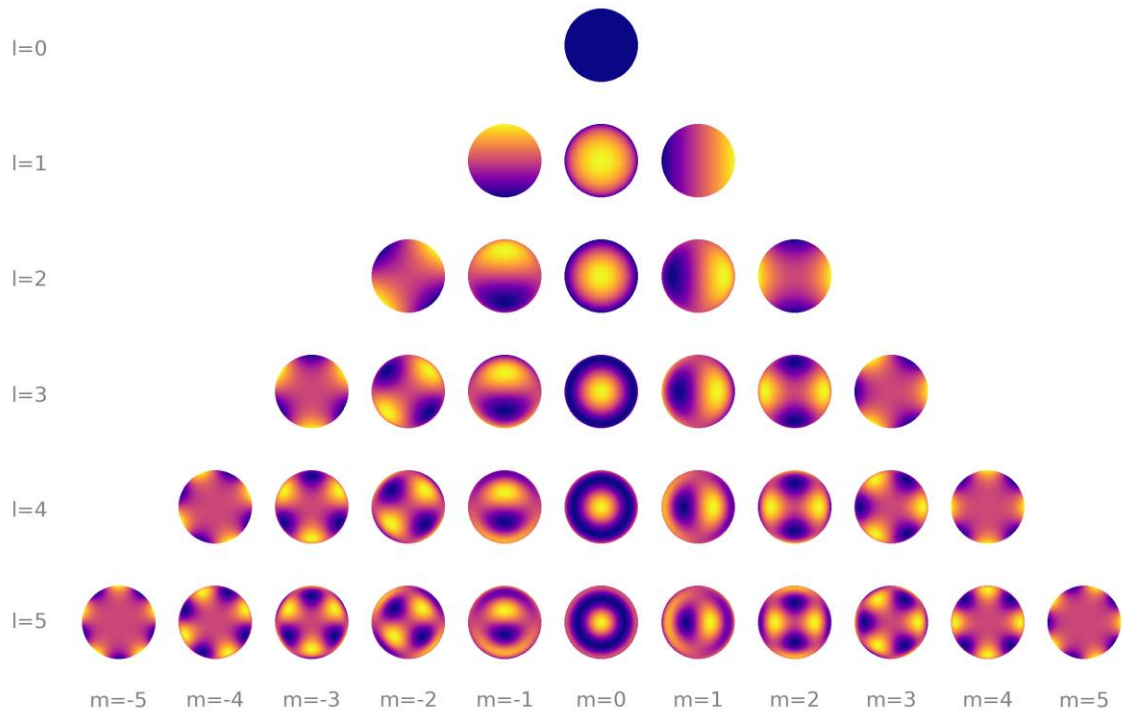
**Need to understand all possible maps consistent with data**

# Spherical Harmonics

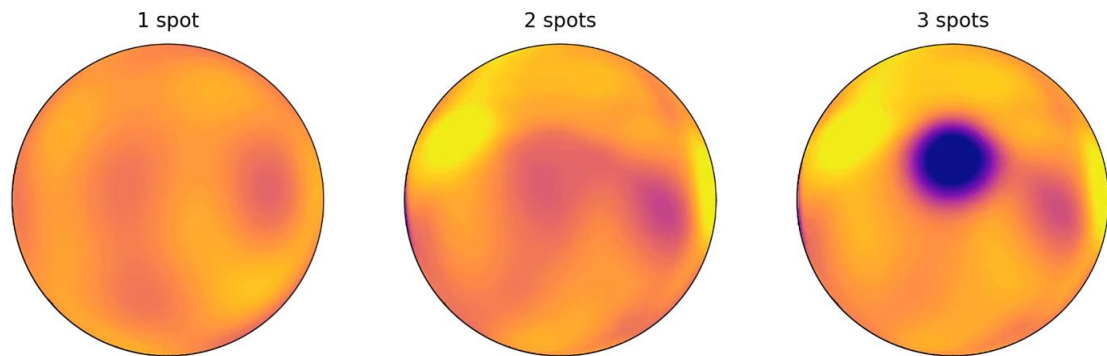
Provides a way of understanding the information theory of the mapping problem

Special set of polynomials on a unit sphere

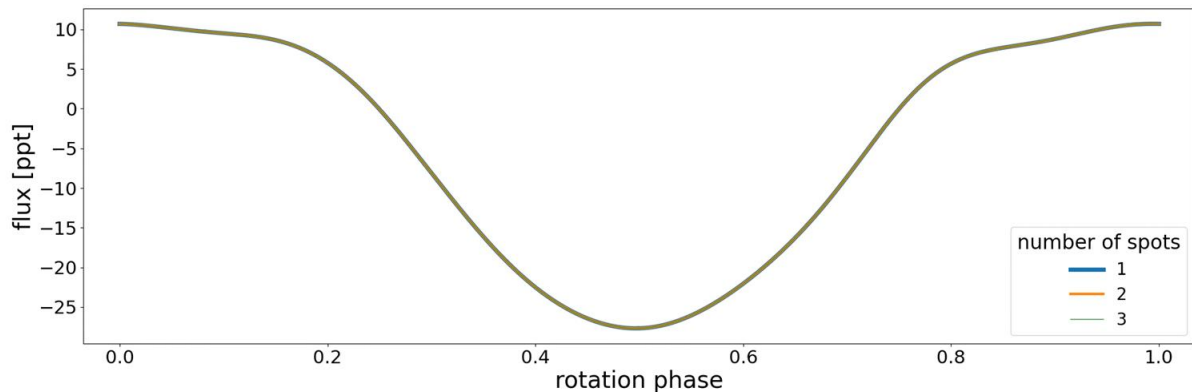
Any surface map can be expressed as a linear combination of spherical harmonics



# The rotational light curve problem



Looking at a star's brightness over time gives you some information about its surface—a disk integrated flux at each unit time



But there are significant degeneracies in mapping stars with just photometry

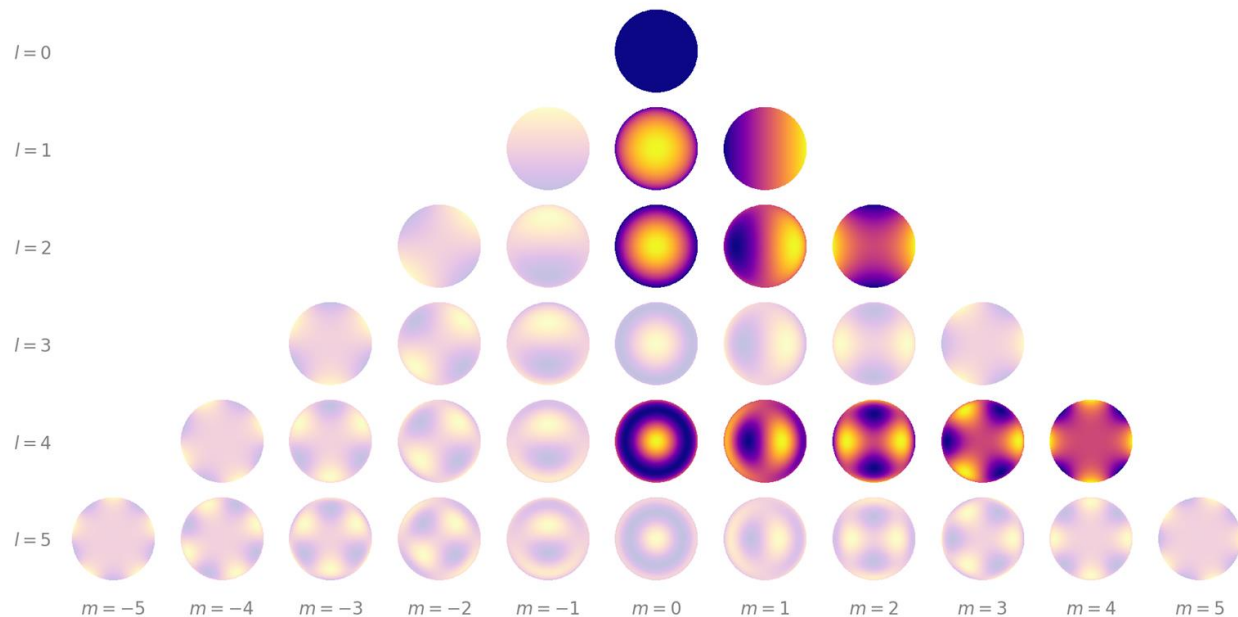
# The null space

$$F = A y$$

Null space is the set of harmonics that do not contribute to the light curve

Most of the information in the map is destroyed when transforming to a light curve

Contains all of the degeneracies of the stellar map



# Spherical Harmonics: Modeling interferometry

$$I(x, y) = \underbrace{\tilde{\mathbf{y}}(x, y)}_{\text{basis}} \underbrace{\mathbf{R}}_{\text{rotation map}} \underbrace{\mathbf{y}}_{\text{map}}$$

Representing intensity in the spherical harmonic basis (read from right to left):

$$V(u, v) = \iint_{S(x, y)} I(x, y) e^{-i(ux+vy)} dx dy$$

van-Cittert Zernike theorem: Fourier transform of the intensity on sky is the complex visibility

$$= \iint_{S(x, y)} \tilde{\mathbf{y}}(x, y) e^{-i(ux+vy)} dx dy \mathbf{R} \mathbf{y}$$

Because of linearity of the Fourier transform, we can remove the dependence of the rotation operation and the  $\mathbf{y}$  inside the integral

$$= \mathfrak{F}[\tilde{\mathbf{y}}(x, y)] \mathbf{R} \mathbf{y}$$

We only need to solve for the FT of the basis itself

# Spherical Harmonic: Analytic solution

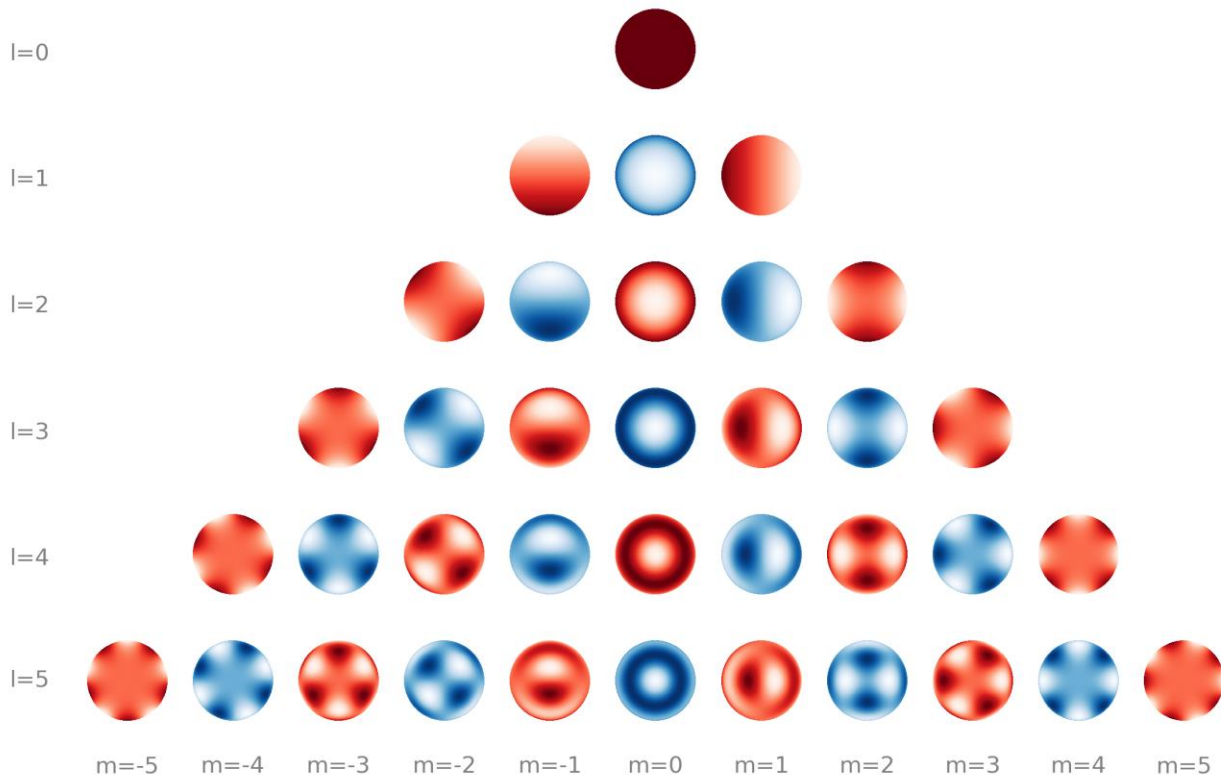
Two families of solutions:

## Hemispheric harmonics

- Solved by changing basis to Zernike polynomials
- Solution in terms of Bessel functions

## Complementary hemispheric harmonics

- Solution in terms of a single spherical Bessel function





# Harmonix

Analytic forwards models of interferometry in Python

Open source and easy to use

Jax: fast and automatically differentiable:

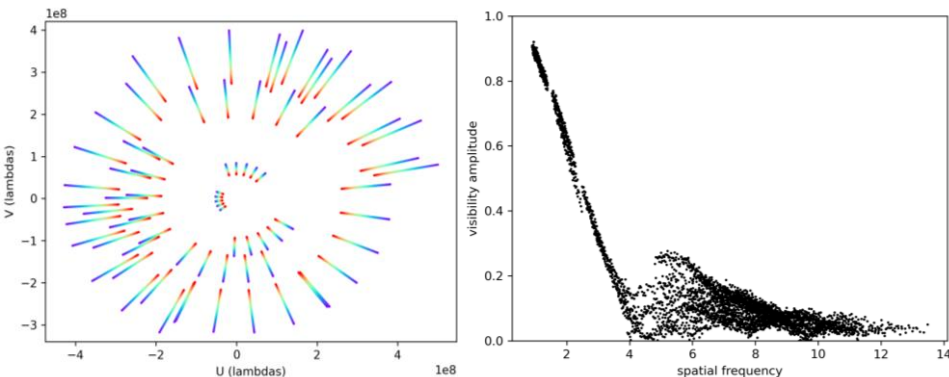
- Gradient-based Monte Carlo for high-dimensional models

Works with other codes in `jax` (`jaxoplanet`) for joint fits to multiple types of observations (interferometry, photometry)

Gives you uncertainties and unlocks information theory

# Information theory of mapping

Simulation of a spotted, resolved star with CHARA/SPICA



Gradients allow computing the Fisher information matrix

- How many bits of information does a dataset permit us to obtain about a star's map?

Properties of Fisher information:

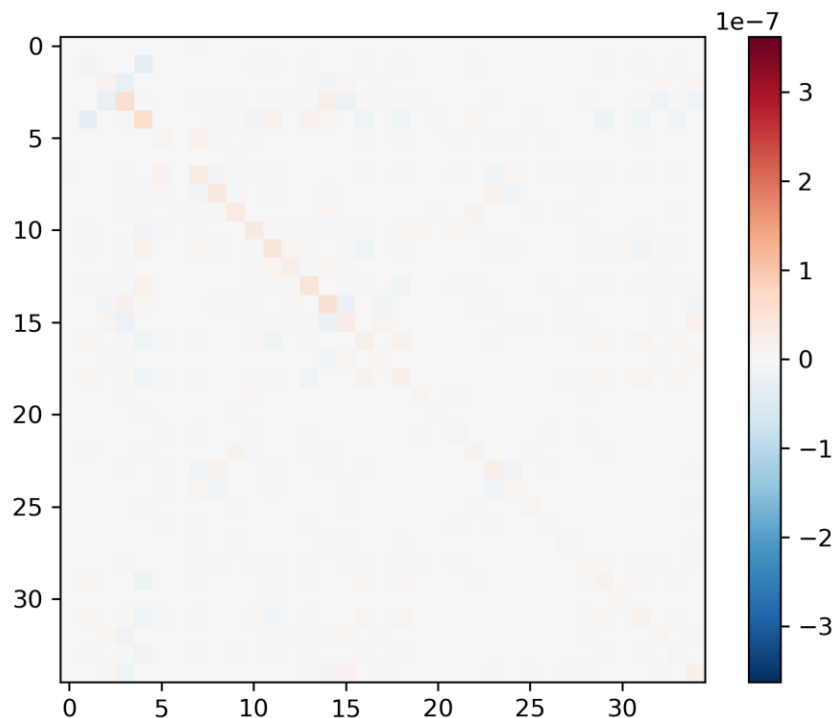
- Multiple datasets can be combined by simply adding their information
- Inverse of the Fisher information matrix at the best-fit parameters is the covariance matrix

# Interferometry + space-based photometry

CHARA does great at high resolution information but doesn't provide coverage at the shortest baselines

Photometry buys back the low-res details

By combining both together, you can get an order of magnitude improvement in stellar surface measurements



Covariance matrix of map coefficients  
How to read: Diagonal is variance on each map coefficient  
White=better constraint

# Future work

- Using `harmonix` to fit observations of rotating, spotted stars
- CHARA observations of Eps UMa upcoming (March 22-27<sup>th</sup>), simultaneously with TESS
- Chaining `harmonix` stars together into binaries (and multiples), solving for orbital parameters & map coefficients simultaneously
- Rewriting starry Doppler imaging into `jax` to allow modelling interferometry, photometry & Doppler imaging simultaneously